Haski the Robot



Final examination project for Advanced Functional Programming 2004

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- The motivation for this project goes back to a progamming course in secondary school
 - We used "Niki der Roboter", a very stripped-down versions of Pascal
 - Originally based on "Karel the Robot" by Richard E.
 Pattis, 1981
 - There are variants for C, Java and the like
- But this one is new:
 - It's all Haskell ! :-)





- Haski the robot is a complete programming environment for the very simple language "Haski"
 - The user controls a small robot on a working area, trying to accomplish various tasks
- Intended for people who have no or very little previous programming experience
- Keep it simple !
 - Very limited choice of commands
 - Only basic syntactical structures



- Haski's main features:
 - A fully-fledged GUI that shows the working area and the robot(s) as they execute the programs
 - A quite sophisticated lexical and syntactical parser for Haski-programs and mapfiles
 - Reads Haski-code and map definitions from files and parses them, creating a suitable data structure which can be used by the GUI and it's underlying interpreter
 - It is independent of GHCi, i.e. it can be compiled and distributed as a stand-alone executable file.
 - Important for usability wrt. unexperienced users
 - An extensive user manual with lots of examples

Let's have a look



- Working area divided into 15x20 fields
- Movement blocked by walls
- Items lying on certain fields
- One or more robots at the same time



Haski commands



- Controlling a robot is simple:
 - The robot understands the following commands:
 - go_forward
 - turn_right
 - take_item
 - drop_item
 - do_nothing
 - It implements some boolean sensors:
 - front_free, left_free, right_free
 - facing_up, facing_right, facing_down, facing_left
 - field_has_item, is_carrying

Writing programs



- Commands can be combined with "&>"
 - turn_right &> go_forward &> take_item
- Four conditional expressions:
 - IfThen <condition> <commands>
 - IfThenElse <condition> <commands> <commands>
 - While <condition> <commands>
 - DoWhile <commands> <condition>
- Condition:
 - Built of sensors or combination of sensors
 - : & for AND, : | for OR, Not for negation

Functions

- A program consists of one or more function definitions:
 - main = While front_free go_forward
 - Every program must have the main-function
- More functions can be defined and used elsewhere:

```
- main = go_forward &>
    IfThen left_free turn_left
    turn_left = turn_right &>
        turn right &>
```





Implementation



- Main steps (rough outline):
 - Implement the GUI and its underlying interpreter
 - Used embedded language in the beginning
 - Build a lexical and syntactical parser for programs
 - Add error handling and meaningful output to parser
 - Build a lexical and syntactical parser for mapfiles
 - Add error handling here as well
 - Add some refinements to the GUI like loading programs and maps and a log-window
 - Bugfixing :-p

Parsing



- Parsing consists of two steps
 - lexer :: String -> [Token]
 - Define list of Tokens using RegEx
 - Haskell-lexer is generated with the tool *Alex*
 - parser :: [Token] -> Program
 - Define a suitable CFG for the language and how it translates to the internal data structure for programs
 - Use *Happy* to generate a Haskell-parser
- Problem with this simple version:
 - On parsing errors the haskell function error "..."
 is called, which is definitely not good style

Parse-error handling



- Monadic approach:
 - Construct a monad for handling and passing errors
 - data Parse a = Ok a | Failed String instance Monad Parse where ...
 - lexer :: String -> Parse [Token]
 parser :: [Token] -> Parse Program
 - Final parser is \s -> lexer s >>= parser
 - We want meaningful error messages
 - Line/column numbers and strings have to be passed around while parsing, which gets pretty messy
 - Monad has to be integrated <u>into</u> the parsing, requires quite some handwork